

STABLE CONVERGENCE WITH APPLICATIONS

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What is it?

A form of convergence of random variables. In statistics, one typically deals with two forms of convergence of random variables.

Convergence in probability $X_n \xrightarrow{p} X$. For every $\varepsilon > 0$,

$$\Pr(|X_n - X| \geq \varepsilon) \rightarrow 0.$$

Convergence in distribution $X_n \xrightarrow{d} X$. For every bounded and continuous function f ,

$$E f(X_n) \rightarrow E f(X).$$

Stable convergence $X_n \xrightarrow{\text{st.}} X$, is weaker than convergence in probability, and stronger than convergence in distribution.

$$X_n \xrightarrow{p} X \Rightarrow X_n \xrightarrow{\text{st.}} X \Rightarrow X_n \xrightarrow{d} X.$$

Why do we need it?

- (i) The Cramér–Slutsky rules don't apply when the limit in probability of the denominator is a proper random variable.
- (ii) Conditionality principle considerations: Often, we want to bring prelimiting information into the limit distribution.
- (iii) Conditioning on a path might mess up the probabilistic structure that is used in the derivation of the asymptotic distribution, for example independence or conditional independence.
- (iv) Simplifies measure change. Derive large-sample results under one ('easy') probability measure, then adjust the limiting distribution back to the true probability measure.
- (v) Localisation. Large-sample results that apply to a stopped (localised) process, apply almost immediately to the full process. For example, we can assume coefficients are bounded, even when they need not be.

(i) The Cramér–Slutsky rules

If X_1, \dots, X_n are i.i.d. random variables with expectation θ and variance σ^2 . The **central limit theorem**

$$\sqrt{n}(\bar{X}_n - \theta) \xrightarrow{d} N(0, \sigma^2).$$

Cramér–Slutsky rules: If $A_n \rightarrow_d A$, and $B_n \rightarrow_p b$, then

$$A_n B_n \rightarrow_d Ab.$$

So if $\hat{\sigma}_n \rightarrow_p \sigma$,

$$\frac{\sqrt{n}(\bar{X}_n - \theta)}{\hat{\sigma}_n} \xrightarrow{d} (1/\sigma)N(0, \sigma^2) = N(0, 1),$$

and we can base inference on θ on the approximation

$$\Pr(\sqrt{n}(\bar{X}_n - \theta) \leq z) \approx \Phi(z/\hat{\sigma}_n).$$

If σ is a proper random variable, the **central limit theorem** above is **not strong enough** for this conclusion.

... might fail when b is a random variable

Let U_1, U_2, \dots be i.i.d. $\text{Unif}(0, 1)$, $(a_n)_{n \geq 1} \subset [0, 1/2]$. Set

$$A_n = \begin{cases} 1, & U_n \in [a_n, a_n + 1/2], \\ 0, & \text{otherwise.} \end{cases}$$

Then A_1, A_2, \dots are i.i.d. $\text{Bernoulli}(1/2)$. Let $B \sim \text{Unif}(0, 1)$. Then $A_n \rightarrow_d A \sim \text{Bernoulli}(1/2)$, and $B \rightarrow_p B$.

$$A_n B = \begin{cases} B, & U_n \in [a_n, a_n + 1/2], \\ 0, & \text{otherwise.} \end{cases}$$

Let $f(x) = \max\{\min(x, 1), 0\}$, and note that f is bounded and continuous. Now,

$$\mathbb{E} f(A_n B) = \int_{a_n}^{a_n + 1/2} v \, dv = \frac{1}{2} \left(a_n + \frac{1}{4} \right).$$

This example is from Häusler and Luschgy (2015).

(ii) The conditionality principle¹

Sir David Cox (1994, p. 442):

How does the long run become relevant to a particular set of data? Well, by being suitably conditioned. The arguments for this seem to me absolutely overwhelming [...]

Famous example from Cox (1958, p. 360): Flip a fair coin X and sample

$$Y \sim N(\theta, \sigma_X^2),$$

where $\sigma_0^2 < \sigma_1^2$. Suppose $X = 1$. What is the ‘correct’ variance of $\hat{\theta} = Y$,

$$\sigma_1^2, \quad \text{or} \quad \frac{\sigma_0^2 + \sigma_1^2}{2}.$$

¹See Barndorff-Nielsen and Cox (1994, p. 34) for a precise definition.

A toy example²

Let $\varepsilon_1, \varepsilon_2, \dots$ be i.i.d., $\Pr(\varepsilon_1 = -1) = \Pr(\varepsilon_1 = 1) = 1/2$. For some $\rho \in (-1, 1)$ set $\sigma_1 = \rho\varepsilon_1$, and $\sigma_i = \sum_{j=1}^{i-1} \rho^j \varepsilon_j$ for $i \geq 2$. We observe

$$X_i = \theta + \sigma_i \varepsilon_i, \quad \text{for } i = 1, 2, \dots,$$

and seek to make inference on θ . By Doob's convergence theorem

$$\sigma_n = \sum_{j=1}^n \rho^j \varepsilon_j \rightarrow \sigma_\infty = \sum_{j=1}^{\infty} \rho^j \varepsilon_j,$$

almost surely, with σ_∞ a random variable. Set

$$\mathbb{E} \exp\{it\sqrt{n}(\bar{X}_n - \theta)\} \rightarrow \mathbb{E} \exp\left(-\frac{t^2 \sigma_\infty^2}{2}\right)$$

thus X_n tends in distribution to a mixed normal limit,

$$\sqrt{n}(\bar{X}_n - \theta) \xrightarrow{d} \mathbb{N}(0, \sigma_\infty^2).$$

²Adapted from Hall and Heyde (1980).

Toy example contd.

But

$$\sqrt{n}(\bar{X}_n - \theta) \xrightarrow{d} N(0, \sigma_\infty^2),$$

cannot be directly used for inference on θ .

- (i) Even though $\hat{\sigma}_n \rightarrow_p \sigma_\infty$, we **cannot** conclude that $\sqrt{n}(\bar{X}_n - \theta)/\hat{\sigma}_n$ tends to a standard normal;
- (ii) Averaging out σ_∞ breaches the conditionality principle;
- (iii) Condition on σ_∞ ? But then we fiddle with the independence of the $\varepsilon_1, \varepsilon_2, \dots$

Definition of stable convergence

A probability space $(\Omega, \mathcal{F}, \Pr)$, and $\mathcal{G} \subset \mathcal{F}$, on which we have a sequence $(X_n)_{n \geq 1}$ with values in a Polish space $(\mathcal{X}, \mathcal{B})$.³ Say that X_n converges \mathcal{G} -stably, and write

$$X_n \Rightarrow X, \quad \mathcal{G}\text{-stably,}$$

if

$$\mathbb{E} Y f(X_n) \rightarrow \int_{\Omega} \int_{\mathcal{X}} Y(\omega) f(x) Q(\omega, dx) \Pr(d\omega),$$

as $n \rightarrow \infty$, for all bounded \mathcal{G} -measurable random variables Y , and all bounded and continuous functions f .

³A complete (all Cauchy sequences converge) and separable (has a countable and dense subset) metric space.

What does this mean? I

Have a sequence X_1, X_2, \dots on $(\Omega, \mathcal{F}, \Pr)$.

Convergence in distribution:

$$\Pr(X_n \in B) = P_n(B) \rightarrow P(B), \quad \text{for all } P\text{-cont. } B,$$

and we ‘realise’ the limit P with a random variable $X \sim P$. Since $\Pr(X_n \in B) = \Pr(X_n \in B \mid \{\Omega, \emptyset\})$, the distributions of $(X_n)_{n \geq 1}$ given the trivial σ -algebra converge.

Stable convergence: Condition on a larger σ -algebra $\mathcal{G} \subseteq \mathcal{F}$ (‘bring more information into the limit’), and

$$\Pr(X_n \in B \mid \mathcal{G}) = Q_n(\cdot, B) \rightarrow Q(\cdot, B),$$

in the sense above. Can regard stable convergence as convergence of conditional distributions.

What does this mean? II

As usual, we would like to ‘realise’ the limiting distribution by a random variable. Construct an extension of the original probability space,

$$\tilde{\Omega} = \Omega \times \mathbb{R}, \quad \tilde{\mathcal{F}} = \mathcal{F} \otimes \mathcal{B}, \quad \tilde{\Pr}(d\omega, dx) = Q(\omega, dx)\Pr(d\omega).$$

Then define a random variable $Y(\omega, x)$ on the extension, such that

$$\Pr(Y \leq y \mid \mathcal{G})(\omega) = Q(\omega, (-\infty, y]).$$

In the toy example, that $\sqrt{n}(\bar{X}_n - \theta)$ converges \mathcal{F} -stably to normally distributed Y , means that

$$Y(\omega, \cdot) \sim Q(\omega, (-\infty, y]) = \int_{-\infty}^y \frac{1}{\sqrt{2\pi}\sigma_{\infty}(\omega)} \exp\left(-\frac{z^2}{2\sigma_{\infty}^2(\omega)}\right) dz.$$

Consequences

If Y_n converges \mathcal{G} -stably to Y , then $Y_n \rightarrow_d Y$ (set $\xi = 1$).

Proposition VIII.5.33 in Jacod and Shiryaev (2003, p. 513). There is equivalence

- (1) $Y_n \Rightarrow Y$ \mathcal{G} -stably;
- (2) $(Y_n, X) \rightarrow_d (Y, X)$ for all \mathcal{G} -measurable X ;
- (3) $(Y_n, X) \Rightarrow (Y, X)$ \mathcal{G} -stably for all \mathcal{G} -measurable X ;
- (4) If $Y_n = (Y_{n,1}, \dots, Y_{n,p})^t$ take values in \mathbb{R}^p , then

$$E I_A \exp(iu^t Y_n) \rightarrow E I_A \exp(iu^t Y), \quad \text{for all } A \in \mathcal{G}.$$

'Stable' Cramér–Slutsky. If A_n converges \mathcal{G} -stably to A , and $B_n \rightarrow_p B$, for \mathcal{G} -measurable B , then

$$A_n B_n \rightarrow_d AB.$$

Pf: By (2), $(A_n, B_n) = (A_n, B) + o_p(1) \rightarrow_d (A, B)$, & cont. mapping.

Convergence in distribution, but not stably

(1) Let X_1, X_2 be independent with distribution function F . Set

$$Y_n = \begin{cases} X_1, & \text{for } n \text{ odd,} \\ X_2, & \text{for } n \text{ even.} \end{cases}$$

Then $Y_n \rightarrow_d F$, but Y_n does not converge stably. If $A = \{X_1 \leq a\}$, then ,

$$\mathbb{E} I_A f(Y_n) = \begin{cases} \mathbb{E} I_A g(X_1), & \text{for } n \text{ odd,} \\ F(a) \mathbb{E} g(X_2), & \text{for } n \text{ even.} \end{cases}$$

(2) Let $X_1 \sim N(0, 1)$, independent of X_2, X_3, \dots , that are i.i.d. with $\mathbb{E} X_2 = 0$ and $\text{Var}(X_2) = 1$. Set $\mathcal{F} = \sigma(X_1, X_2, X_3, \dots)$, and

$$Y_n = \frac{1}{\sqrt{2}} X_1 + \frac{1}{\sqrt{2}\sqrt{n}} \sum_{i=2}^n X_i.$$

Then

$$Y_n \xrightarrow{d} N(0, 1),$$

but Y_n does not converge \mathcal{F} -stably to a $N(0, 1)$.

Applications

- (1) Supercritical Galton–Watson processes.
- (2) Critical AR(1) processes.
- (3) Stochastic volatility models with leverage effect.

Supercritical Galton–Watson processes

$(Y_{n,j})_{n,j \geq 1}$ i.i.d. $\text{Poisson}(\theta)$. Suppose that $X_0 = 1$, and set

$$X_n = \sum_{j=1}^{X_{n-1}} Y_{n,j}.$$

Assume that $\theta > 1$.⁴ Using that X_1, X_2, \dots is a Markov chain, the log-likelihood is

$$\ell_n(\theta) = \sum_{j=1}^n \{x_j(\log \theta + \log x_{j-1}) - \theta x_{j-1} - \log x_j!\},$$

and by solving $\partial \ell_n(\theta) / \partial \theta = 0$ we find

$$\hat{\theta}_n = \frac{\sum_{j=1}^n X_j}{\sum_{j=1}^n X_{j-1}}, \quad \text{so} \quad \hat{\theta}_n - \theta = \frac{\sum_{j=1}^n (X_j - \theta X_{j-1})}{\sum_{j=1}^n X_{j-1}}.$$

⁴If $\theta \leq 1$, then $\lim_{n \rightarrow \infty} X_n = 0$ almost surely (Williams, 1991, Ch. 0).

Supercritical Galton–Watson processes contd.

The conditional variance process is

$$\sum_{j=1}^n \mathbb{E} \{ (X_j - \theta X_{j-1}) \mid \mathcal{F}_{j-1} \} = \sum_{j=1}^n \text{Var}(X_j \mid \mathcal{F}_{j-1}) = \theta \sum_{j=1}^n X_{j-1}.$$

Since $\theta^{-n} X_n$ is a martingale (and $\sup_n \mathbb{E} |\theta^{-n} X_n|^2 < \infty$),

$$\frac{\sum_{j=1}^n X_{j-1}}{\sum_{j=1}^n \theta^{j-1}} = \frac{\sum_{j=1}^n \theta^{j-1} \theta^{-(j-1)} X_{j-1}}{\sum_{j=1}^n \theta^{j-1}} \xrightarrow{p} M_\infty,$$

by Doob's convergence theorem, and Toeplitz lemma. But M_∞ is a **proper random variable**. Since $\sum_{j=1}^n \theta^{j-1} \sim \theta^n / (\theta - 1)$,

$$\frac{\theta - 1}{\theta^n} \sum_{j=1}^n \mathbb{E} \{ (X_j - \theta X_{j-1}) \mid \mathcal{F}_{j-1} \} \xrightarrow{p} M_\infty.$$

Critical AR(1)-type process

Consider $X_j = \theta(j/n)X_{j-1} + \varepsilon_j$ for $j = 1, \dots, n$, with $\theta(t)$ some function on $[0, 1]$, $X_0 = 0$, and $\varepsilon_1, \varepsilon_2, \dots$ i.i.d. with $E\varepsilon_1 = 0$, $\text{Var}(\varepsilon_1) = 1$, and $E\varepsilon_1^4 < \infty$. Test $H_0: \theta(t) = 1$.

For $t \in (0, 1]$, the least squares estimator is

$$\hat{\theta}_n(t) = \frac{\sum_{j/n \leq t} X_{j-1} X_j}{\sum_{j/n \leq t} X_{j-1}^2}.$$

Under H_0

$$n(\hat{\theta}_n(t) - 1) = \frac{\sum_{j/n \leq t} X_{j-1} \varepsilon_j}{\sum_{j=1}^n X_{j-1}^2},$$

and using the Skorokhod embedding

$$\frac{1}{n} \sum_{j/n \leq t} X_{j-1} \varepsilon_j = \int_0^{t_*/n} W_n(s) dW_n(s) + o_p(1),$$

where $W_n(t) = B(tn)/\sqrt{n} \stackrel{d}{=} B_t$, and $t_* = \max\{t_i : t_i \leq nt\}$ for stopping times t_1, t_2, \dots

Critical AR(1)-type process contd.

By an application of Itô's lemma $dW(s)^2 = 2W(s) dW(s) + ds$,

$$\frac{1}{n} \sum_{j/n \leq t} X_{j-1} \varepsilon_j = \frac{W_n(t_*/n)^2 - t_*/n}{2} + o_p(1).$$

Since $n^{-1} \mathbb{E} t_* = n^{-1} \text{Var}(\sum_{i/n \leq t} \varepsilon_i) = [nt]/n \rightarrow t$, and $n^{-2} \mathbb{E} t_*^2 \leq n^{-2} 4 \mathbb{E} \varepsilon_1^4$, we get $t_*/n \rightarrow_p t$. By continuity of $t \mapsto W_n(t)$

$$\frac{1}{n} \sum_{j/n \leq t} X_{j-1} \varepsilon_j \xrightarrow{d} \frac{B_t^2 - t}{2},$$

If we show that this convergence is stable (which it is), then

$$\left(\frac{1}{n} \sum_{j/n \leq t} X_{j-1} \varepsilon_j, \frac{1}{n^2} \sum_{i/n \leq t} X_{i-1}^2 \right) \xrightarrow{d} \left(\frac{B_t^2 - t}{2}, \int_0^t B_s^2 ds \right),$$

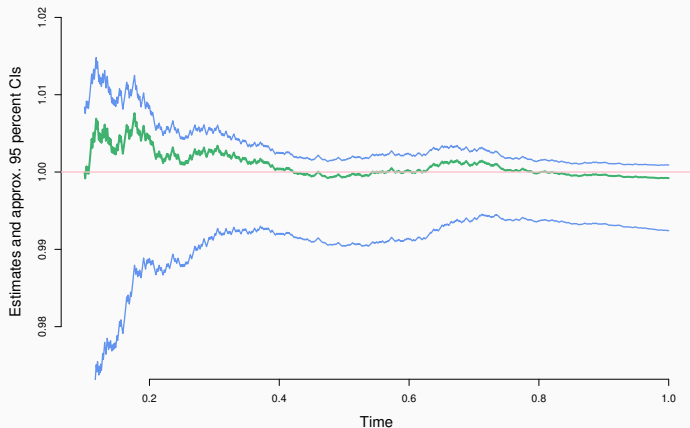
and we can conclude

$$n(\widehat{\theta}_n(t) - 1) \xrightarrow{d} \frac{B_t^2 - t}{2 \int_0^t B_s^2 ds}.$$

Simulations

With $n = 1\,000$, $\sigma = 1$, and H_0 true $\theta(t) = 1$, and $\varepsilon_1, \varepsilon_2, \dots$ i.i.d.

$$\Pr(\varepsilon_i = 1) = \Pr(\varepsilon_i = -1) = 1/2.$$



Volatility estimation

Consider the process

$$dX_t = \mu_t dt + \sigma_t dW_t, \quad t \in [0, T],$$

where $X_0 = x_0$, W_t is a one-dimensional Wiener process, and the volatility σ_t^2 is itself a non-negative continuous Itô-process that might in part be driven by W_t . X_t is observed at times

$$0 = t_0 < t_1 < \dots < t_{n-1} < t_n = T,$$

and $t_{j+1} - t_j = T/n$ for all j . Want inference on the *integrated volatility*

$$\theta_t = \int_0^t \sigma_s^2 ds, \quad \text{at time } T.$$

That the *realised volatility*

$$\hat{\theta}_t^n = \sum_{t_{j+1} \leq t} (X_{t_{j+1}} - X_{t_j})^2 \xrightarrow{P} \int_0^t \sigma_s^2 ds = \theta_t, \quad (1)$$

is a fundamental fact about (semi-)martingales (Jacod and Shiryaev, 2003, Theorem I.4.47, p. 52).

Volatility estimation contd.

One finds that

$$\widehat{\theta}_t^n - \theta_t = M_t^n + o_p(n^{-1/2}),$$

where M_t^n is the continuous time martingale

$$M_t^n = 2 \sum_{t_{j+1} \leq t} \int_{t_j}^{t_{j+1}} (X_s - X_{t_j}) dX_s + 2 \int_{t_*}^t (X_s - X_{t_*}) dX_s,$$

with $t_* = \max\{t_{j+1} : t_{j+1} \leq t\}$.

Heuristic argument:

$$(X_s - X_{t_j})^2 = \left(\int_{t_j}^s \sigma_u dW_u \right)^2 \approx (s - t_j) \sigma_{t_j}^2.$$

The predictable quadratic variation,

$$\begin{aligned} \langle M^n, M^n \rangle_{(t_j, t_{j+1}]} &= \int_{t_j}^{t_{j+1}} (X_s - X_{t_j})^2 \sigma_s^2 ds \\ &\approx \int_{t_j}^{t_{j+1}} (s - t_j) \sigma_{t_j}^4 ds = \frac{(t_{j+1} - t_j)^2}{2} \sigma_{t_j}^4. \end{aligned}$$

Volatility estimation contd.

$$n\langle M^n, M^n \rangle_t \xrightarrow{p} 2T \int_0^t \sigma_s^4 ds, \quad \text{for all } t$$

and by a martingale CLT (Mykland and Zhang, 2012, p. 152),

$$n^{1/2}(\widehat{\theta}_T^n - \theta_T) \rightarrow \left(2T \int_0^T \sigma_t^4 dt\right)^{1/2} Z$$

stably in distribution, where $Z \sim N(0, 1)$ is independent of $\int_0^T \sigma_t^4 dt$. Due to the stability of this convergence

$$\frac{n^{1/2}(\widehat{\theta}_T^n - \theta_T)}{c_n} \xrightarrow{d} N(0, 1),$$

where c_n^2 is a consistent estimator of $2T \int_0^T \sigma_t^4 dt$ (see Mykland and Zhang (2012, Theorem 2.28, pp. 137–138) for such an estimator).

Martingale central limit theorems

Two theorems for continuous martingales, here stated for continuous martingales, both extend to the càdlàg case.

Theorem 3.6. (Helland, 1982, p. 88) *Let M^n be a sequence of continuous local martingales on $[0, T]$. Suppose that there is a measurable function f such that*

$$\langle M^n, M^n \rangle_t \xrightarrow{P} \int_0^t f^2(s) ds, \quad \text{for all } t.$$

Then $M^n \Rightarrow \int f dW$, where W_t is a one-dimensional Wiener process.

(G): \mathcal{F}_t is generated by independent Wiener processes $W_t^{(1)}, \dots, W_t^{(p)}$, for some $p \geq 1$.

Theorem 3.7. (Zhang (2001), Mykland and Zhang (2012), p. 152) *Assume (G). Let M^n be a sequence of continuous local martingales on $[0, T]$. Suppose that there is a \mathcal{F}_t -adapted process f_t such that*

$$\langle M^n, M^n \rangle_t \xrightarrow{P} \int_0^t f^2(s) ds, \quad \text{for all } t,$$

and that for $j = 1, \dots, p$

$$\langle M^n, W^{(j)} \rangle_t \xrightarrow{P} 0, \quad \text{for all } t. \tag{8}$$

Then $M^n \Rightarrow \int f dW$ \mathcal{F} -stably, where W_t is a one-dimensional Wiener process defined on an extension.

The independent-of-data condition

Stable convergence is weak convergence conditionally on (parts) of the data. Need something more concrete than a σ -algebra to represent the data:

$$\mathcal{F}_t = \sigma(W_t^{(1)}, \dots, W_t^{(p)}) = \sigma(\text{indep. Wiener processes}),$$

is sufficient when dealing with continuous processes. When trying to show that $M^n \Rightarrow M = \int f dW'$, we must ensure that M^n tends to something that is uncorrelated with the $W^{(1)}, \dots, W^{(p)}$, that is, $\langle M^n, W^{(j)} \rangle_t \rightarrow_p 0$ for all j .

The Lévy-characterisation (Karatzas and Shreve, 1991, p. 157): The following are equivalent

- 1) $(X^{(1)}, \dots, X^{(k)})$ is a standard Wiener process;
- 2) $X_t^{(i)} X_t^{(j)} - \delta_{i,j} t$ is a local martingale for $1 \leq i, j \leq k$;
- 3) $[X^{(i)} X^{(j)}]_t = \delta_{i,j} t$ for $1 \leq i, j \leq k$,

where $\delta_{i,j} = 1$ if $i = j$ and $\delta_{i,j} = 0$ otherwise, the Kronecker delta.

Check the independence condition

Let $dX_t = \sigma_t dW_t$, for $t \in [0, 1]$, with W a 1-dim. Wiener process, and set

$$M_t^n = 2n^{1/2} \sum_{t_{j+1} \leq t} \int_{t_j}^{t_{j+1}} (X_s - X_{t_j}) dX_s + 2n^{1/2} \int_{t_*}^t (X_s - X_{t_*}) dX_s,$$

The **tricity**

$$n^{1/2}[X, X, X]_t^n = n^{1/2} \sum_{t_{n,i+1} \leq t} (X_{t_{n,i+1}} - X_{t_{n,i}})^3,$$

is consistent for $[M^n, X]_t$. If $t_{n,i+1}$ are, for example, fixed and equidistant times $t_{n,i+1} - t_{n,i} = 1/n$, then

$$n^{1/2}[X, X, X]_t^n = \sum_{t_{n,i+1} \leq t} (X_{t_{n,i+1}} - X_{t_{n,i}})^3 \approx \frac{1}{n} \sum_{t_{n,i+1} \leq t} N(0, \sigma_{t_{n,i}}^2)^3,$$

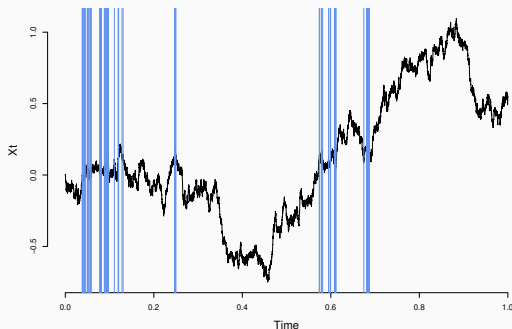
which tends to zero in probability, $EN(0, \sigma^2)^3 = 0$. Thus,

$[X, X, X]_t^n \rightarrow_p v_t \neq 0$, is closely related to the **skewness of the increments** $X_{t_{n,i+1}} - X_{t_{n,i}}$.

Endogenous observation times

Let X_t be a 1-dim. Wiener process. We observe X_t at $t_{n,0} = 0$, and

$$t_{n,i+1} = \text{smallest } t > t_{n,i} \text{ s.t. } \begin{cases} X_t - X_{t_{n,i-1}} = n^{-1/2}a, \text{ or} \\ X_t - X_{t_{n,i-1}} = -n^{-1/2}b, \end{cases} \quad , a, b > 0$$



A version of Example 4 is in Li et al. (2014, p. 590).

Endogenous observation times contd.

Then

$$X_{t_{n,i}} - X_{t_{n,i-1}} \stackrel{d}{=} n^{-1/2}Y, \quad \text{where } Y = \begin{cases} a, & \text{with prob. } \frac{b}{a+b}, \\ -b, & \text{with prob. } \frac{a}{a+b}. \end{cases},$$

independent. Importantly,

$$\mathbb{E} (X_{t_{n,i}} - X_{t_{n,i-1}})^3 = \frac{a-b}{n^{3/2}},$$

so non-zero skewness when $a-b \neq 0$, and $n^{1/2}[X, X, X]_t^n \xrightarrow{P} a-b$.

Can ‘fix’ this by constructing a martingale (finding a process g_s)

$$\widetilde{M}_t^n = M_t^n - \int_0^t g_s dX_s, \quad \text{so that } \langle \widetilde{M}^n, X \rangle_t \xrightarrow{P} 0,$$

and adjusting back to get

$$M_t^n \Rightarrow \int_0^t a_s dX_s + \int_0^t b_s dW'_s, \quad \mathcal{F}\text{-stably.}$$

which is a \mathcal{F} -conditional Gaussian martingale (Jacod and Shiryaev, 2003, p. 130).

Relationship to standard asymptotics

Suppose that Z_1, Z_2, \dots are i.i.d. random variables with

$$\mathbb{E} Z_1 = 0, \quad \text{Var}(Y) = \sigma^2, \quad \zeta = \frac{\mathbb{E} Z^3}{\sigma^3}, \quad \kappa = \frac{\mathbb{E} Z^4}{\sigma^4}.$$

Estimator $\hat{\sigma}_n^2 = n^{-1} \sum_{i=1}^n Z_i^2$, and

$$\sqrt{n}(\hat{\sigma}_n^2 - \sigma^2) \xrightarrow{d} \text{N}\{0, \sigma^4(\kappa - 1)\}.$$

Consider

$$\tilde{\sigma}_n^2 = \frac{1}{n} \sum_{i=1}^n Z_i^2 - \hat{c}_n \frac{1}{n} \sum_{i=1}^n Z_i, \quad \text{with} \quad \hat{c}_n = \frac{\sum_{i=1}^n Z_i^3}{\sum_{i=1}^n Z_i^2} \xrightarrow{p} \frac{\mathbb{E} Z_1^3}{\mathbb{E} Z_1^2} =: c,$$

where c minimises

$$\text{Var}(Z_1^2 - cZ_1) = \sigma^4(\kappa - 1) + c^2\mathbb{E}[Z_1^2] - 2c\mathbb{E}[Z_1^3]$$

$$\begin{aligned} \sqrt{n}(\tilde{\sigma}_n^2 - \sigma^2) &= \frac{1}{n} \sum_{i=1}^n (Z_i^2 - cZ_i) - (\hat{c}_n - c) \frac{1}{n} \sum_{i=1}^n Z_i \\ &= \frac{1}{n} \sum_{i=1}^n (Z_i^2 - cZ_i) + o_p(1) \xrightarrow{d} \text{N}\{0, \sigma^4(\kappa - 1 - \zeta^2)\}. \end{aligned}$$

Measure change and stable convergence

Suppose

$$dX_t = \mu_t dt + \sigma_t dW_t, \quad X_0 = x_0,$$

with W a Wiener process under P , and that we observe X_t at discrete time $0 \leq t_{n,0}, \dots, t_{n,n} \leq T$. It can be easier to derive large-sample results when X_t is a martingale, rather than a semimartingale, that is

$$dX_t = \sigma_t dW'_t, \quad X_0 = x_0,$$

with W' a Wiener process under P' .

The probabilities P and P' are mutually absolutely continuous (see Girsanov's theorem, Karatzas and Shreve (1991, Corollary 3.5.2, p. 192)) and the Radon–Nikodym derivative dP/dP' is \mathcal{F} -measurable. Let $Y_n = \sqrt{n}(\hat{\theta}_T^n - \theta_T)$, as above, and assume that $Y_n \Rightarrow Y$ \mathcal{F} -stably under P' . For bounded & cont. g , and bounded \mathcal{F} -meas. ξ ,

$$E_P \xi g(Y_n) = E_{P'} \frac{dP}{dP'} \xi g(Y_n) \rightarrow E_{P'} \frac{dP}{dP'} \xi g(Y) = E_P \xi g(Y),$$

see Mykland and Zhang (2009, Prop. 1, p. 1408).

Localisation and stable convergence

An example from Mykland and Zhang (2012, pp. 156–161): When proving that

$$Y_n = n^{1/2}(\hat{\theta}_T^n - \theta_T) \rightarrow (2T \int_0^T \sigma_t^4 dt)^{1/2} Z = Y, \quad \text{stably,}$$

it is convenient to **assume that $\sigma_t^2 \leq \sigma_+^2$** , for all t , where σ_+^2 is some constant. Stable convergence makes it possible to **relax this assumption**, and **instead assume that σ_t^2 is locally bounded**. That is, there is a sequence $\tau_1 < \tau_2 < \tau_3 < \dots$ of stopping times such that

$$\Pr(\lim_{m \rightarrow \infty} \tau_m = T) = 1, \quad \text{and} \quad \sigma_t^2 \leq \sigma_{m,+}^2, \text{ for } 0 \leq t \leq \tau_m.$$

For if $Y_n \Rightarrow T$ \mathcal{F} -stably, then $\xi I_{\{\tau_m \leq T\}}$ is \mathcal{F} -measurable

$$\mathbb{E} \xi I_{\{\tau_m \leq T\}} f(Y_n) \rightarrow \mathbb{E} \xi I_{\{\tau_m \leq T\}} f(Y),$$

and

$$\begin{aligned} & |\mathbb{E} \xi f(Y_n) - \mathbb{E} \xi f(Y)| \\ & \leq |\mathbb{E} \xi I_{\{\tau_m \leq T\}} f(Y_n) - \mathbb{E} \xi I_{\{\tau_m \leq T\}} f(Y)| + \max_y |f(y)| \Pr(\tau_m > T). \end{aligned}$$

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Some additional details on the AR(1) example i

The denominator in the expression for $\hat{\theta}_n(t)$ is

$$Z_n(t) = \frac{1}{n} \sum_{j/n \leq t} X_{j-1} \varepsilon_j.$$

Since $X_0 = 0$, for $j = 1, \dots, n$, we have $X_j = \sum_{i=1}^j \varepsilon_i$, and by the Skorokhod embedding, there are stopping times $t_1 \leq t_2 \leq \dots$, so that

$$X_j = \sum_{i=1}^j \varepsilon_i = B(t_j), \quad \text{and} \quad \varepsilon_j = B(t_j) - B(t_{j-1}), \quad \text{for } j = 1, 2, \dots,$$

for a Brownian motion B , where we take $t_0 = 0$. Set

$W_n(t) = B(nt)/\sqrt{n} \stackrel{d}{=} B_t$ by Brownian scaling. We can now write

$$\begin{aligned} Z_n(t) &= \sum_{j/n \leq t} \frac{1}{\sqrt{n}} B(t_{j-1}) \frac{1}{\sqrt{n}} \{B(t_j) - B(t_{j-1})\} \\ &= \sum_{j/n \leq t} W_n(t_{j-1}/n) \{W_n(t_j/n) - W_n(t_{j-1}/n)\} \\ &= \int_0^{t^*/n} W_n(s) dW_n(s) + o_p(1), \end{aligned}$$

Some additional details on the AR(1) example ii

where $t_* = \max\{t_j : t_j \leq nt\}$, and the $o_p(1)$ term is

$$\sum_{j/n \leq t} \int_{t_{j-1}/n}^{t_j/n} \{W_n(s) - W_n(t_{j-1}/n)\} dW_n(s) = o_p(1),$$

By Itô's formula

$$Z_n(t) = \int_0^{t_*/n} W_n(s) dW_n(s) + o_p(1) = \frac{W_n(t_*/n)^2 - t_*/n}{2} + o_p(1).$$

Since $t_*/n \rightarrow_p t$, and $t \mapsto W_n(t)$ is continuous,

$$Z_n(t) \xrightarrow{d} \frac{B_t^2 - t}{2}.$$

For the claims in the slides above, it is also important to argue that

$$(n^{-1} \sum_{j/n \leq t} X_{j-1} \varepsilon_j, n^{-2} \sum_{j/n \leq t} X_{j-1}^2),$$

converges jointly. Then finish up the proof of finite-dim. convergence, and check tightness, to get full process convergence.